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1	<u>Three-dimensional kinematic differences between accurate and high</u>		
2	velocity kicks in rugby union place kicking.		
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20	Abstract		
20	ADSTRACT		
21	Place kicking occurs many times during a rugby union game with more than half of all points		
22	scored coming from place kicking. Ball velocity is an important biomechanical indicator of		
23	kicking success but it also evident that the ball must be kicked accurately to pass between the		
24	posts. This study aimed to identify biomechanical differences in rugby place kicking		
25	kinematics when kicking towards a specific target and for maximum velocity. Ten male		

26 rugby union kickers performed place kicks in two conditions 1. for maximum velocity and 2. 27 towards a pre-defined target. Lower extremity kinematics were obtained using an optoelectric motion capture system operating at 500 Hz. Differences in lower extremity 28 kinematics between the two kicking conditions were examined using paired t-tests. Higher 29 ball velocities were obtained when kicking for maximum velocity. Foot linear velocity, knee 30 extension velocity and hip extension velocity were also found to be greater when kicking for 31 maximum velocity. Ankle dorsiflexion and peak external rotation were found to be greater in 32 the accuracy condition. The findings suggest that rugby kickers may have selected distinct 33 34 kicking mechanics characterised by reduced joint angular velocities and a more externally rotated foot position in a deliberate attempt to improve precision, sacrificing ball velocity and 35 thus the distance that the ball can be kicked. The specific findings from the current work have 36 implications for coaches and applied practitioners which may facilitate improvements in 37 kicking performance. 38

39

## 40 Introduction

Place kicking is used frequently during rugby union games (Baktash et al., 2009), and is now
a key determinant of success in the modern game. Of the total points scored in 2012 by the
highest seeded international sides, more than half of all points scored come from place
kicking either in the form of a conversion or a penalty (Sinclair et al., 2014).

45

Like soccer instep kicks, place kicks involve a series of motions that include an initial address to the ball, planting of the support leg beside the ball, and striking of the ball with the instep of the kicking foot (Barfield 1995; Lees & Nolan 1998). Whilst the basic mechanical actions of the place kick are similar to the instep kick in soccer players, differences in ball shape, tee support, and release angles make the place kicking technique unique (Baktash et al., 2009; Bezodis et al., 2009; Zhang et al., 2011).

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53 The release velocity of the ball is considered the main biomechanical indicator of kicking 54 success in most sports that involve stationary kicking and it is the result of various factors, 55 including technique (Lees & Nolan, 1998). As such place kicking for maximal resultant ball velocity is desirable, particularly in modern rugby union where kicks in excess of 50 m are not uncommon (Zhang et al., 2011). Nonetheless, whilst it is clear that the ball must be struck with sufficient velocity to reach the posts it is also evident that the ball must be kicked accurately in order for it to pass between the posts to allow the points to register. The analysis of accurate kicks has however received little attention compared with maximal velocity kick biomechanics in rugby place kicking analyses.

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Place kicking analyses in soccer have shown differences when kicking accurately and for 63 maximum ball velocity. Godik et al. (1993) found that higher ball velocities were associated 64 with the greatest level of accuracy in players who executed instep kicks at their own approach 65 speed. Conversely, when soccer players were instructed to kick the ball with the highest 66 possible velocity, higher approach velocities were linked to less accurate kicking mechanics. 67 Lees and Nolan (1998) showed that when a player is instructed to perform a kick accurately 68 there is a reduction in ball velocity and also in angular velocities of the lower extremity 69 joints. Teixeira et al. (1999) found that soccer kicks aimed towards a defined target were 70 associated with longer duration and smaller ankle displacement and velocity compared with 71 kicks performed towards an undefined target. The research cited above suggests that the 72 target determines the actual constraints on accuracy; its manipulation leads to a trade-off 73 between speed and accuracy of the kick. In other words, when the player is required to 74 75 perform an accurate kick, then the approach as well as the joint rotations and velocities are 76 also lower compared with those recorded during a powerful kick.

77

78 Despite the depth of research in soccer-specific analyses, knowledge regarding rugby union 79 place-kicking remains largely unexplored in biomechanics literature. Specifically, there does 80 not appear to be any published information regarding the potential trade-off between accurate kicking and the generation of ball velocity. Therefore, this study aimed to identify 81 biomechancal differences in rugby place kicking kinematics when kicking towards a specific 82 target and for maximum velocity. A study of this nature may be of practical significance to 83 place kickers and coaches, who wish to better understand the differences in mechanics under 84 85 different constraints pertinent to successful kicking execution,

86

#### 87 Methods

#### 88 *Participants*

Ten male participants volunteered to take part in this investigation (age  $22.4 \pm 1.2$  years; height  $1.81 \pm 0.07$  m; body mass  $86.1 \pm 4.2$  kg). All participants were regular place kickers at University first team level. All were free from musculoskeletal injury and provided written informed consent in accordance with the declaration of Helsinki. Ethical approval for this project was obtained from the School of Sport Tourism and Outdoors ethical committee at the University of Central Lancashire.

95

## 96 *Procedure*

Kinematic information was obtained using an optoelectric motion capture system with 8 97 cameras (Qualisys Medical AB, Gothenburg, Sweden) using a capture frequency of 500 Hz. 98 Each participant performed place kicks of a standard rugby ball (Gilbert Virtuo, size 5) into a 99 100 net positioned 8 m away in two conditions. In the maximum velocity kicking condition participants were instructed simply to kick the ball as hard as they could into the net. In the 101 accuracy constrained condition participants were instructed to kick the ball towards a 0.5 x 102 0.5 m square positioned 5 m behind the net onto the wall of the biomechanics laboratory. 103 104 The rugby ball was placed on a kicking tee positioned such that participants were able to adopt their preferred approach towards the ball. An additional four retroreflective markers 105 106 were positioned onto the surface of the rugby ball, at one end of its longitudinal axis. Football contact was delineated using the initial displacement of these markers. Ten trials were 107 108 obtained for each participant in each of the two conditions. The order in which participants performed in each of the conditions was counterbalanced. 109

110

The current investigation used the calibrated anatomical systems technique (CAST) to 111 112 quantify angular kinematics (Cappozzo et al., 1995). To define the anatomical axes of the right and left feet, shanks and thigh segments, retroreflective markers were positioned 113 114 bilaterally onto the calcaneus, 1st and 5th metatarsal heads, medial and lateral malleoli, medial and lateral epicondyle of the femur and greater trochanter. To delineate the pelvic 115 116 segment co-ordinate axes, additional markers were positioned onto the anterior (ASIS) and posterior (PSIS) superior iliac spines. The hip joint centre was estimated using a regression 117 118 technique based on the ASIS marker separation (Sinclair et al., 2013). Rigid carbon fiber

tracking clusters with four non-linear retroreflective markers were positioned onto the pelvis, shank and thigh segments. Static calibration trials (not normalised to standing posture) were obtained for each participant to allow the anatomical positions of the retroreflective markers to be referenced in relation to the tracking clusters. Following the acquisition of the calibration trial markers not used for tracking were removed.

124

## 125 Data-processing

Discrete 3-D kinematic parameters were quantified using Visual 3-D (C-Motion Inc, 126 Germantown MD, USA) and filtered at 15 Hz using a zero-lag low pass Butterworth 4th 127 order filter. Joint rotations were created using an XYZ sequence of rotations referenced to co-128 ordinate axes created about the proximal end of the segment. 3-D kinematic measures from 129 the hip, knee and ankle from the stance and kicking limbs which were extracted for statistical 130 analysis were 1) angle at ball impact, 2) peak angle, 3) range of motion from stance limb 131 contact to ball impact, 4) peak range of motion from foot contact to peak angle, 5) angular 132 133 velocity at ball impact and 6) peak angular velocity. In addition to this linear ball velocity 134 was also obtained. Finally, the duration of the kick phase from stance limb foot contact to ball impact and the medial-lateral distance from the kicking foot to the ball were extracted. 135

136

#### 137 Statistical analyses

138 Means and standard deviations of 3-D kinematic parameters were calculated for each kicking condition. Differences in these parameters were examined using paired samples t-tests. The 139 140 alpha criterion was adjusted using a Bonferroni adjusted alpha criterion ( $p \le 0.0005$ ) to control type I error. Effect sizes for all significant tests were quantified using partial eta squared ( $\eta^2$ ). 141 Effect sizes were characterized in accordance with Cohen (1988), small = 0.2, medium = 0.5, 142 and large = 0.8. In accordance, with the Winter et al., (2014) an effect size of >0.2 was 143 considered to be practically important. The data were also screened for normality using a 144 Shapiro-Wilk which conformed that the normality assumption was met. Statistical analyses 145 were conducted using SPSS 21.0 (SPSS Inc, Chicago, USA). 146

147

## 148 **Results**

Figures 1-4 present the mean 3-D angular kinematics of the hip, knee and ankle joints for the
stance and kicking limbs. Tables 1–4 present the 3-D kinematic parameters from the hip,
knee and ankle observed as a function of kicking condition.

152

## 153 Velocity, distance and temporal measures

The results showed that ball velocity was greater (t (9) = 5.61, p<0.0005,  $\eta^2 = 0.78$ ) when 154 kicking for maximum velocity ( $28.6 \pm 2.3 \text{ m.s}^{-1}$ ) in comparison to accuracy ( $25.0 \pm 2.6 \text{ m.s}^{-1}$ ). 155 Release angle was not different (t (9) = 1.25, p>0.0005,  $\eta^2 = 0.15$ ) between maximum 156 velocity  $(27 \pm 7^{\circ})$  and accurate  $(29 \pm 4^{\circ})$  kicks. Foot linear velocity was greater (t (9) = 4.76, 157 p<0.0005,  $\eta^2 = 0.78$ ) when kicking for maximum velocity (22.4 ± 2.5 m.s<sup>-1</sup>) in comparison to 158 accuracy ( $19.2 \pm 3.0 \text{ m.s}^{-1}$ ). In addition, no (t (9) = 3.91, p>0.0005,  $\eta^2 = 0.63$ ) differences 159 were observed between maximum velocity ( $0.38 \pm 0.04$  m) and accurate ( $0.34 \pm 0.07$  m) for 160 the horizontal distance from the plant foot to the ball. Finally, it was observed that there was 161 no difference (t (9) = 3.30, p>0.0005,  $n^2 = 0.55$ ) in the duration of the kick phase between 162 maximum velocity  $(0.13 \pm 0.02 \text{ s})$  and accurate kicking  $(0.11 \pm 0.02 \text{ s})$ . 163

164

165 *Kicking limb* 

166	<b>@@@</b> Figure 1 near here @@@
167	@@@ Figure 2 near here @@@
168	@@@ Table 1 near here @@@
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The results show in the sagittal plane that peak hip flexion angular velocity was greater (t (9) = 5.11, p<0.0005,  $\eta^2 = 0.74$ ) when kicking for maximal velocity when compared to accurate kicking. Furthermore, knee extension angular velocity at ball contact was also shown to be greater (t (9) = 6.21, p<0.0005,  $\eta^2 = 0.81$ ) in the maximum velocity condition in comparison to the accuracy condition. Finally, it was revealed that that ankle was (t (9) = 5.78, p<0.0005,  $\eta^2 = 0.79$ ) more plantar-flexed in the maximum velocity condition compared to when kicking for accuracy. In the transverse plane the results indicate that in the accuracy condition that the

ankle was (t (9) = 5.09, p<0.0005,  $\eta^2 = 0.74$ ) more externally rotated at ball contact in 178 comparison to kicking for maximum velocity. Finally, it was also shown that the ankle 179 transverse plane rotation angular velocity was different (t (9) = 6.13, p<0.0005,  $\eta^2 = 0.81$ ) 180 between the two conditions at ball contact, with the accuracy condition showing the ankle to 181 be externally rotating and the maximum velocity showing the ankle to be internally rotating. 182 183 184 Stance limb 185 @@@ Figure 3 near here @@@ 186 @@@ Figure 4 near here @@@ 187 188 @@@ Table 3 near here @@@ 189 @@@ Table 4 near here @@@ 190 191

192 The results show in the transverse plane that peak hip internal rotation was (t (9) = 5.61, 193 p<0.0005,  $\eta^2 = 0.78$ ) greater when kicking for maximal velocity when compared to accurate 194 kicking. Finally, it was also shown that peak ankle internal rotation was greater (t (9) = 5.29, 195 p<0.0005,  $\eta^2 = 0.76$ ) when kicking for maximal velocity when compared to accurate kicking.

196

# 197 Discussion

198 The aim of the current investigation was to determine the 3-D kinematic differences in rugby 199 place kicking kinematics when kicking towards a specific target and for maximum velocity. 200 This represents the first investigation to compare the biomechanics of rugby place kicking 201 when kicking for maximum velocity and when kicking for accuracy.

202

203 With regards to ball velocity, the results of the current investigation are to be expected and show that kicking for maximum velocity is associated with greater ball velocity than when 204 kicking for accuracy. This is supported by the increases in knee extension angular velocity 205 and foot linear velocity at impact when kicking for maximum velocity. This observation 206 supports the findings of Sinclair et al. (2014) who showed that knee extension velocity was 207 correlated with ball velocity during rugby place kicking. The findings from the current 208 209 investigation appear to support those from soccer in-step kicking analyses regarding the existence of a speed/accuracy trade-off (Plamondon & Alimi, 1997; Teixeira et al., 1999) in 210 211 that the alterations in kicking mechanics necessary to promote accuracy were used at the expense of maximising ball velocity. 212

213

In addition, it was also observed that peak hip flexion angular velocity was also greater when 214 215 kicking for maximum velocity. This supports the notion that the velocity of the distal segments is resolved via a pattern of segmental interactions termed the proximal to distal 216 217 sequence. Hip flexion angular velocity contributes to about 50% of the resultant angular velocity of the more distal segments (Putnam, 1993). During the second half of the kick 218 219 movement the hip flexion velocity is reduced as the knee extension velocity increases. Although the thigh angular velocity is decreased in the latter part of the kick phase it is 220 nonetheless important when ball velocity is desirable to generate greater hip flexion velocities 221 222 in order to angular velocity to the distal segments.

223

224 A further significant observation occurred at the ankle in both sagittal and transverse planes. 225 It was found that the ankle was more dorsiflexed and externally rotated at ball contact, when 226 kicking for accuracy. This finding concurs with those from soccer based analyses which have 227 documented similar findings in accurate kicks in comparison to when kicking for maximum velocity (Lees & Nolan, 2002; Teixeira, 1999). It is hypothesized that this observation relates 228 to the kicking mechanics used by participants when kicking for accuracy. In order to 229 maximize accuracy participants may have used a more side foot technique by externally 230 rotating the ankle in order to ensure ball contact with the medial aspect of the foot. This is 231 supported by Levanon & Dapena (1998) who theorized that side foot or kicking in soccer is 232 employed when there is a requirement for precision. Increased dorsiflexion ensures that the 233 contact point is closer to the metatarsals than the ankle. Kellis and Katis, (2007) showed that 234

when the ball is kicked with the aspect of the foot near the ankle, the ball is released with amuch greater linear velocity.

237

In modern rugby union a significant number of points are now secured from place kicking, 238 making successful execution of place kicks vital to the final outcome. The current 239 investigation has importantly characterized the mechanics of both accurate and high velocity 240 241 rugby union place kicks. Therefore based on the findings from the current work, coaches and applied practitioners should be encouraged to emphasize the importance of generating high 242 knee angular velocity in kickers who are striving to generate greater kicking distance. This 243 may involve exercises which develop explosive power in the quadriceps muscle group which 244 serve to extend the joint. Conversely in kickers who are seeking to improve the accuracy of 245 their place kicks should be encouraged to focus on drills which promote increased 246 dorsiflexion and external rotation of the foot at the instance of ball contact. This may 247 ultimately enable kickers to combine these two key aspects and increase the likelihood of 248 victory for their team. 249

250

251 A limitation of the current investigation is the laboratory based nature of the data collection procedures. Firstly, whilst accuracy was the focus of one of the experimental conditions it 252 could not be specifically examined, rather the participants were instructed simply to aim for a 253 254 specific target positioned onto the laboratory wall. In addition, the confines of the laboratory may also have affected the ecological validity of the ball release characteristics. Linthorne & 255 Stokes (2014) demonstrated in a field based experiment that the optimum projection angle is 256 around 30°, with increasing projection angles leading to reductions in ball release velocity. 257 258 Thus it appears that the trials examined during this study may not be truly not representative of a kick at goal. Future field based analyses may wish to consider the effects of accurate and 259 maximum velocity kicking mechanics. A further limitation is the playing level of the 260 participants used in this experiment. A sample of skilled yet not elite rugby union place 261 kickers was tested as part of this investigation. This indicates that the observations may not 262 be generalizable to populations outside this study. Future work should seek to quantify 263 mechanical differences between accurate and maximum velocity kicks in more skilled place 264 kickers. 265

In conclusion, the current investigation has demonstrated that differences in kicking mechanics exist when kicking for accuracy when compared to kicking for maximum velocity. It is likely that kickers may have chosen utilize these mechanics when kicking for accuracy in a deliberate attempt to improve precision, but at the expense of sacrificing ball velocity and thus the distance that the ball can be kicked. Therefore, the specific findings from the current work have implications for coaches and applied practitioners which may facilitate improvements in kicking performance.

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- 327

## 328 Figures

- Figure 1: Hip, knee and ankle joint kinematics from the kicking limb as a function of the
  dominant and non-dominant limbs (black = max velocity & dash = accuracy).
- Figure 2: Hip, knee and ankle joint angular velocities parameters from the kicking limb as a
- function of the dominant and non-dominant limbs (black = max velocity & dash = accuracy).
- Figure 3: Hip, knee and ankle joint kinematics from the stance limb as a function of the dominant and non-dominant limbs (black = max velocity & dash = accuracy).
- Figure 4: Hip, knee and ankle joint angular velocities parameters from the stance limb as a
- function of the dominant and non-dominant limbs (black = max velocity & dash = accuracy).